



IGNITED MINDS
Journals

*Journal of Advances in
Science and Technology*

*Vol. 10, Issue No. 21,
February-2016, ISSN 2230-
9659*

REVIEW ARTICLE

A NEW APPROACH FOR AVAILABILITY ANALYSIS

AN
INTERNATIONALLY
INDEXED PEER
REVIEWED &
REFEREED JOURNAL

A New Approach for Availability Analysis

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The researchers have discussed the reliability and availability of many stochastic systems and process industries by using very cumbersome and time-consuming techniques. The general formulae in the closed form are not yet developed to determine the key parameters for a semi Markov renewal process like mean time to system failure (MTSF), availability of the system, and busy periods of the servers doing different jobs, the number of server's visits and the number of replacements of the components/sub-systems. Chander, S. & Mukender Singh [14], Goyal, Rashmi & Ashok Kumar [40], Tuteja, R.K. et al. [110] and many others, have analyzed and discussed various systems under steady state conditions, using the following formulae of the regenerative point technique to find the key parameters of a stochastic system:

- a) $MTSF = \lim_{s \rightarrow 0} \frac{1}{s} \mathbf{S}$
- b) $Availability = \lim_{s \rightarrow 0} \mathbf{A}(s) = \lim_{s \rightarrow 0} \frac{1}{s} \mathbf{A}(s)$
- c) $Busy\ period\ of\ the\ server = \lim_{s \rightarrow 0} \mathbf{B}(s) = \lim_{s \rightarrow 0} \frac{1}{s} \mathbf{B}(s)$
- d) $Expected\ number\ of\ server's\ visits / replacements = \lim_{s \rightarrow 0} \frac{1}{s} \mathbf{V}(s)$

Where \mathbf{S} is obtained on solving recursively the state governing equations after taking the Laplace Stieltjes Transformations (L.S.T.) of each of the state renewal equation, written for each un-failed regenerative state using the equation:

$$t_i(t) = I_j Q_{ij}(t) \otimes t_j(t) + \sum_k \mathbf{1}_{ij}(t) \otimes t_k(t) \quad \dots\dots\dots(2.1.1)$$

Where t_i is an un-failed regenerative state to which the given regenerative state t_j can transit and t_k is a failed state to which the state t_j can transit directly.

$\mathbf{V}(s)$ is obtained on solving recursively the state governing equations after taking the Laplace Transformations (L.T.) of the state renewal equations, written for each regenerative state using the renewal equation:

$$MO = M_i(t) + \sum_j L_{q_j}(t) \otimes A_j(t) \quad \dots\dots\dots(2.1.2)$$

Where t_j is any successive regenerative state to which the regenerative state T can transit through $n > 1$ transitions. $\mathbf{V}(s)$ is obtained as stated for $\mathbf{V}(s)$, using renewal equation:

$$Bf(t) = W_i(t) + \sum_j Z_{q_j}(t) \otimes B_j(t) \quad \dots\dots\dots(2.1.3)$$

Where t_j is a successive regenerative state to which state t_i transits through $n > 1$ transitions.

$\mathbf{V}(s)$ is obtained on solving recursively the governing equations after taking the Laplace Stieltjes Transformations (L.S.T.) of the state renewal equations, written for each regenerative state using the equation:

$$V_i(t) = I_j Q_{ij}(t) \otimes [S_j + V_j(t)] \quad \dots\dots\dots(2.1.4)$$

Where t_j is any regenerative state to which the given regenerative state t_i transits; $S_j = 1$, if t_j is the regenerative state where the server enters afresh/replacement begins, otherwise $S_j = 0$.

Further, the researchers analyzed the systems without giving the due consideration to the reduced states where the system is not fully available because of its partial failure(s).

A new approach for the analysis of a stochastic system is introduced in this chapter. In addition, the concept of the fuzziness measure of the states is introduced to deal with the working of the system in reduced states. This new approach is illustrated in Section 2.6. The statistical models/formulae are presented in the closed form by the equations (2.5.1) to 35 (2.5.4). These are quite easy to apply without using any lengthy and cumbersome calculations, to find the key parameters of a semi-Markov process with underlying Markov renewal process represented by a finite, ir-reducible and aperiodic Markov chain.

FIRST PASSAGE TIME

The probability density function (p.d.f.) of the first passage time from a regenerative state i to a regenerative state j or to a failed state j , without visiting any other regenerative state in $(0, t]$ is defined as

$$f_{i,j}(t) = P\{X_n = j | X_0 = i, \text{ no } k \text{ visited in } (0, t]\}$$

where X_n denotes the state of the system at n -th epoch of time.

The cumulative distribution function (c.d.f.) of the first passage time from a regenerative state i to a regenerative state j or to a failed state j , without visiting any other regenerative state in $(0, t]$, given that the system entered regenerative state i at $t = 0$, is defined as

$$F_{i,j}(t) = P\{X_n = j | X_0 = i, \text{ no } k \text{ visited in } (0, t]\}$$

It is the probability of transition from a regenerative state i to the regenerative state j without visiting any other regenerative state in the interval $(0, t]$, given that the system entered regenerative state i at $t = 0$. It is also denoted as $f_{i,j}(t)$.

Further, since for a finite, irreducible, aperiodic Markov chain, the probability of transition $f_{i,j}(t)$ becomes independent of the initial state i and it tends to a finite limit as $t \rightarrow \infty$.

This limiting value is called the steady-state transition probability of the state j and is given by

$$p_{i,j} = \lim_{t \rightarrow \infty} f_{i,j}(t) = \lim_{t \rightarrow \infty} \int_0^t f_{i,j}(t-u) q_i(u) du$$

The steady-state probability of a simple path from the state i (initial state) to the state j (terminal state) is defined as the probability of transition from the state i to the state j along a given directed simple path $(i \rightarrow j)$.

Let $P_{i,j} = \{q_{i,j}, q_{i,j}^2, \dots, q_{i,j}^n\}$ given directed simple path from the state i to the state j in the transition diagram of the system where no k -cycle is formed for $A: a_1, a_2, \dots, a_n$ are not the terminals of any circuit in the transition diagram. Let the first passage transition times from a_1 to a_2, a_2 to a_3, \dots, a_{n-1} to a_n are variables $X_1, X_2, X_3, \dots, X_n$ having the probability density functions as $q_1(t), q_2(t), \dots, q_n(t)$ respectively. The p.d.f. of the stochastic variable: $S_n = X_1 + X_2 + X_3 + \dots + X_n$ is defined by

$$q(t) = q_1(t) \otimes q_2(t) \otimes q_3(t) \otimes \dots \otimes q_n(t), \quad \text{Cox [15]}$$

$$q(t) = \int_0^t q_1(t-u) q_2(u) du$$

On taking Laplace transformation

Therefore, probability of the given simple path $(i \rightarrow j)$ under steady-state conditions, is given by

$$pr(a_0 \rightarrow a_n) = \int_0^\infty q(t) dt = \lim_{s \rightarrow 0} \frac{q(s)}{s} = q^*(0)$$

$$= q_1^*(0) q_2^*(0) \dots q_n^*(0)$$

$$= \sum_{i=0}^n P_{i,j}$$

Symbolically,

$$pr(a_0 \rightarrow a_n) = (a_0, a_1, a_2, \dots, a_n) V^n$$

STEADY STATE TRANSITION PROBABILITY OF A REACHABLE STATE

The steady-state transition probability of a state j reachable from the state i is defined as the sum of the steady-state path probabilities of transition from the state i to the state j along all the directed simple paths $(i \rightarrow j)$ for different values of V , from the state i to the state j .

A simple path $(i \rightarrow j)$ for a given value of V , from the state i to the state j in the state-transition diagram may have the regenerative state(s) k at which k -cycle(s) are formed. The steady-state transition probability of the state j reachable from the state i (denoted by $V_{i,j}$) is the conditional probability defined by

$$V_{i,j} = \frac{pr(i \xrightarrow{sr} j)}{\sum_k pr(k \text{- cycle})} \quad (2.4.1)$$

where k is a regenerative state belonging to the simple path $(i \rightarrow j)$ where k -cycle(s) are formed. And $\sum_k pr(k \text{- cycle})$ is the sum of probabilities of all the different k -simple circuit(s) formed at the given regenerative point k and for a given value of r .

If k is a regenerative point belonging to the given simple path $(i \rightarrow j)$ such that no k -cycle is formed, then $V_{i,j} = 0$. And if for a fixed V the simple path $(i \rightarrow j)$ has one or more regenerative path point(s) where k -cycle(s) are formed in the transition diagram of the system, then all such state(s) k are considered for the calculation of $V_{i,j} = \sum_k pr(k \text{- cycle})$, k The steady-state transition probability $V_{i,j}$ of the state j reachable from the initial

state $l = 0$ (at $t = 0$) is $\sum_j J_{l,j}$ and it forms the probability distribution $\langle V_{0,j} \rangle = \sum_j V_{0,j} P_{0,j}$ stochastic variable y .

A Particular Case: In particular, if l and j are consecutive regenerative states in the transition diagram of the system and $(l \rightarrow j) = \{i, j\}$ be the only simple path, then

$$pr(l \rightarrow j) = \frac{P_{l,j}}{(0-U)0-L_j} \dots\dots\dots(2.4.2)$$

where $L_k = \sum_j V_{k,j}$, $k = \sum pr(k - cycle)$.

And further, if no cycles are formed at l and j states, then $L_l = 0$, $L_j = 0$. And in this case the steady-state transition probability of a state l reachable from the state l' is

$$pr(l \rightarrow j) = P_{l,j} \dots\dots\dots (2-4.3)$$

A NEW APPROACH FOR AVAILABILITY ANALYSIS

On considering the concepts explained in Sections 2.3 and 2.4, the vital and key parameters like mean time to system failure (MTSF), availability of the system, busy periods for inspection/ instructions/ repairs/ replacements and the number of visits by different servers doing different types of jobs such as inspection/ instructions/ repairs/ replacements; the number of different types of replacements and the number of preventive & corrective maintenance actions can be evaluated by using the formulae (2.5.1) to (2.5.4) explained as follows:

Mean Time To System Failure (MTSF):

The mean time to failure of a system is the statistical average time for which the system is operative before any failure(s) of the system. The term *MTSF* is used when the system undergoes either preventive or corrective maintenance actions. Mean time to system failure (under steady state conditions) of the system is given by $\sum_j V_{0,j} / \lambda$ where i is an un-failed l regenerative state in the state-transition diagram of the system. On using (2.4.1), the mean time to system failure is

$$MTSF = \sum_j \frac{\{pr(0 \rightarrow j)\}}{pr(k_2 - cycle)} U_{i=0} \dots\dots\dots (2.5.1)$$

Explanation:

i : a regenerative un-failed state to which the system can transit before entering any failed state while entering the initial 0-state at time $t = 0$.

k_1 : a regenerative state along the path $(0 \rightarrow \dots \rightarrow i)$, at which a k_1 - cycle is formed through regenerative un-failed states.

k_2 : a regenerative state along the path $(0 \rightarrow \dots \rightarrow 0)$, at which k_2 - cycle is formed through regenerative un-failed states.

[In the numerator, the coefficient of $\sum_j J_{l,j}$, for $l = 0$, is equal to $pr(0 \rightarrow 0) = (0, 0) = 1$, and in the denominator the expression also contributes the term $1 - (0, 0) = 1 - P_{0,0}$ provided there is a loop at the 0-state].

Steady State Availability Of A System:

It is defined as the proportion of time that the system is operational when the time- interval is very large and the corrective, preventive maintenance down times and the waiting times are included.

$$AO = \frac{MTBM}{MTBM + MDT}$$

Where *MTBM* = mean time between maintenance; *MDT* (mean down time) = statistical mean of the down times caused due to breakdowns, including supply down time, administrative down time.

The state transition diagram takes into account all the times under consideration of the stochastic system/process (under steady state conditions).

Therefore, $\sum_j V_{0,j}$ measure of the numerator

and $\sum_i V_{0,i}$ measure of the denominator, where l' is a reachable un-failed and is a regenerative state in the state-transition diagram of the system, $\sum_j U_j$ is the total un-conditional time spent before transiting to any other regenerative state(s), given that the system entered regenerative state at $t = 0$. Thus, steady state availability of a system is given by

$$AO = \frac{[\sum_j V_{0,j} \cdot \sum_j U_j] + [\sum_j V_{0,j} \cdot \langle u \rangle]}{\dots\dots\dots}$$

In case the system fails partially and is not fully available for its purpose then the availability of the system is discounted according to the proportions to the fuzziness measure of the states that the system can visit. Accordingly, the steady state availability of a system is modified to

$$A_0 = \sum_j [H V_{0j} - f_j \cdot j U_j] * \sum_i i^{\wedge} V_{0j} - j u_j]$$

where / • is the fuzziness measure of the un-failed state

On using (2.4.1), the steady state availability of a system is

$$A_0 = \frac{\sum_{j,s,r} \{pr(0 \rightarrow j) \cdot M\} \cdot n \{i-iM \cdot \sum_{e} \{e\}\}}{\sum_{i \neq 0} \{i-iM \cdot \sum_{e} \{e\}\}}$$

Explanation:

The 0- state is the state at time t = 0.

j: a reachable state which is an available state (which may be down/ or reduced state). *i*: a regenerative state.

ytj-(^O): a regenerative path-point (may be an interior or the terminal point of the path) at which a *kf* cycle is formed (may be formed through non-regenerative/failed-states). *kl* is a regenerative state visited along the path (0—^{Sr} >/) and $\sum_{i} i$ can be equal to *j*. And \sum_{2} is a regenerative state visited along the path (0—^{Sr} >*j*) and *k2* can be equal to [In the numerator coefficient of *juj*, for *j* = 0, is equal to *pr*(0 -> 0) = (0,0) = 1 and in the denominator coefficient of *ju*, for *l* = 0, is *pr*(0 -> 0) = (0,0) = 1].

In case a down state of the system is treated as a failed state then for availability purposes the said state is to be treated as un-available state.

Busy Period of the Server:

Busy period of the server (under steady state conditions) doing a given job is defined by

$$= \frac{MTTR^{B_0}}{MTBM + MDT}$$

Where *MTTR* = mean time to repair; *MTBM* = mean time between maintenance; *MDT* = mean down time. (*MDT* is replaced by *M* or *MTTR* as per the real situation to which the stochastic process is subjected during its operation).

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